## AXISYMMETRIC DYNAMIC CONTACT PROBLEM FOR A VISCOELASTIC

HALF-SPACE IN THE PRESENCE OF ADHESION UNDER THE STAMP

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The steady vibrations of a rigid stamp of circular planform adhering to the surface of a viscoelastic half-space subjected to a harmonic axial force are considered. There are no forces outside the region of contact.

The system of dual integral equations constructed by using the Hankel transform is reduced to a system of singular integral equations regularized according to Vekua [1]. An approximate solution, valid for small vibrations frequencies, is found. Oscillatory behavior of the stresses is proved. Abramov [2] detected a similar fact in the plane case.

The static problem for an elastic medium has been examined by a number of authors [3-6]. None of the listed papers detected the oscillatory behavior of the stresses at the edge of the stamp.

1. The complex amplitudes of the displacements of a viscoelastic medium in the presence of axial symmetry satisfy the system of equations

$$\begin{aligned} (\lambda_{*} + 2\mu_{*}) &\frac{\partial \Delta}{\partial r} + \mu_{*} \frac{\partial}{\partial z} (2\omega_{\varphi}) = -\rho \omega^{2} u_{r} \end{aligned} \tag{1.1} \\ (\lambda_{*} + 2\mu_{*}) &\frac{\partial \Delta}{\partial z} - \mu_{*} \frac{1}{r} \frac{\partial}{\partial r} (2r\omega_{\varphi}) = -\rho \omega^{2} u_{z} \end{aligned} \\ \Delta &= \frac{1}{r} \frac{\partial}{\partial r} (ru_{r}) + \frac{\partial}{\partial z} u_{z}, \qquad 2\omega_{\varphi} = \frac{\partial}{\partial z} u_{r} - \frac{\partial}{\partial r} u_{z} \end{aligned} \\ \lambda_{*} &= \lambda \Big[ 1 - \int_{0}^{\infty} \Lambda (x) e^{-i\omega x} dx \Big], \qquad \mu_{*} = \mu \Big[ 1 - \int_{0}^{\infty} M (x) e^{-i\omega x} dx \Big] \end{aligned}$$

Here  $\rho$  is the density of the medium,  $\omega$  is the vibrations frequency,  $\lambda_*$  and  $\mu_*$  are the complex moduli.

Let us assume that the medium occupies the half-space  $z \leq 0$ . By using the Hankel transform, we obtain the amplitudes of the displacements in the following form from (1,1):

$$u_{z} = \int_{0}^{\infty} \left[ pe^{pz}A(\omega, s) - \Theta(se^{qz} - pe^{pz})sB(\omega, s) \right] J_{0}(rs) ds$$

$$u_{r} = -\int_{0}^{\infty} s \left[ e^{pz}A(\omega, s) + \Theta(se^{pz} - qe^{qz})B(\omega, s) \right] J_{1}(rs) ds$$

$$p = (s^{2} - k_{1}^{2})^{1/2}, \quad q = (s^{2} - k_{2}^{2})^{1/2}, \quad \Theta = (k_{2}^{2} - k_{1}^{2})^{-1}$$

$$k_{1}^{2} = \frac{\rho\omega^{2}}{\lambda_{*} + 2\mu_{*}}, \quad k_{2}^{2} = \frac{\rho\omega^{2}}{\mu_{*}}, \quad \operatorname{Re} k_{1} \ge 0, \quad \operatorname{Re} k_{2} \ge 0$$

$$(1.2)$$

Here  $A(\omega, s)$  and  $B(\omega, s)$  are unknown functions and p and q are branches of the roots which satisfy the conditions Re  $p \ge 0$ , Re  $q \ge 0$ . The stress amplitudes are obtained from (1.2) as

$$\frac{1}{2\mu_{*}}\sigma_{z} = \int_{0}^{\infty} [\kappa e^{pz}A - \Theta(qse^{qz} - \kappa e^{pz})sB] J_{0}(rs) ds \quad (1.3)$$
$$\frac{1}{2\mu_{*}}\tau_{rz} = -\int_{0}^{\infty} s [pe^{pz}A + \Theta(pse^{pz} - \kappa e^{qz})B] J_{1}(rs) ds$$
$$(\kappa = s^{2} - k_{2}^{2}/2)$$

The boundary conditions on the surface z = 0

$$u_z = f(r), u_r = 0$$
 for  $r < R; \sigma_z = \tau_{rz} = 0$  for  $r \ge R$ 

should be used to determine A and B. Letting z tend to 0, we obtain a system of dual equations from (1.2) and (1.3)

$$\int_{0}^{\infty} [pA - \Theta(s - p) sB] J_{0}(rs) ds = f(r)$$

$$r < R$$

$$\int_{0}^{\infty} s [A + \Theta(s - q) B] J_{1}(rs) ds = 0$$

$$\int_{0}^{\infty} [\varkappa A - \Theta(qs - \varkappa) sB] J_{0}(rs) ds = 0$$

$$r \ge R$$

$$\int_{0}^{\infty} s [pA + \Theta(ps - \varkappa) B] J_{1}(rs) ds = 0$$
(1.5)

2. Analogously to the method developed in [7], let us assume

$$\varkappa A - \Theta (qs - \varkappa) sB = s \int_{0}^{R} \varphi_{1}(t) \cos(ts) dt \qquad (2.1)$$
$$pA + \Theta (ps - \varkappa) B = -\int_{0}^{R} \varphi_{2}(t) \sin(ts) dt$$

The relationships (2.1) are a linear system of equations in A and B. The functions  $\varphi_1(t)$  and  $\varphi_2(t)$  are assumed bounded and continuously differentiable in the halfinterval [0, R). Substituting (2.1) into (1.3) and using the formulas for differentiation of the Bessel functions, we obtain that at z = 0

$$\frac{1}{2\mu_*}\sigma_z = \frac{1}{r} \frac{d}{dr} \int_0^R \varphi_1(t) \left[ \int_0^\infty r J_1(rs) \cos(ts) ds \right] dt$$
$$\frac{1}{2\mu_*} \tau_{r_2} = -\frac{d}{dr} \int_0^R \varphi_2(t) \left[ \int_0^\infty J_0(rs) \sin(ts) ds \right] dt$$

From the properties of the Weber-Schafheitlin integrals [8] as well as the properties of  $\varphi_1(t)$  and  $\varphi_2(t)$  there results that  $\sigma_z = \tau_{rz} = 0$  for  $r \ge R$ . The relationships

$$\frac{1}{2\mu_*}\sigma_z = -\frac{1}{r}\frac{d}{dr}\int_r^n \frac{t\varphi_1(t)\,dt}{V\,t^2-r^2}\,,\qquad \frac{1}{2\mu_*}\,\tau_{rz} = -\frac{d}{dr}\int_r^n \frac{\varphi_2(t)\,dt}{V\,t^2-r^2}\,\,(2.2)$$

hold under the stamp. Eliminating A and B from (1.4) and (2.1), we obtain the system  $\sum_{n=1}^{\infty} \frac{R}{n}$ 

$$\begin{cases} \int_{0}^{\infty} \int_{0}^{R} \left[ g_{11}\varphi_{1}(t)\cos(ts) + \alpha g_{12}\varphi_{2}(t)\sin(ts) \right] J_{0}(rs) dt ds = \beta f(r) \end{cases}$$
(2.3)  
$$\int_{0}^{\infty} \int_{0}^{R} \left[ \alpha g_{21}\varphi_{1}(t)\cos(ts) + g_{22}\varphi_{2}(t)\sin(ts) \right] J_{1}(rs) dt ds = 0$$
  
$$g_{11}(k_{1}, k_{2}, s) = \frac{\beta k^{2} ps}{2D}, \qquad g_{22}(k_{1}, k_{2}, s) = \frac{\beta k^{2} qs}{2D}$$
  
$$g_{12}(k_{1}, k_{2}, s) = g_{21}(k_{1}, k_{2}, s) = -\frac{\gamma s^{2} (pq - \varkappa)}{D}$$
  
$$\left( \alpha = \frac{\mu_{*}}{\lambda_{*} + 2\mu_{*}}, \quad \beta = \frac{\lambda_{*} + \mu_{*}}{\lambda_{*} + 2\mu_{*}}, \quad \gamma = \frac{\beta}{\alpha}, \quad k = k_{2}, \quad D = pqs^{2} - \varkappa^{2} \right)$$

An analysis of the behavior of  $g_{ij}$  at infinity shows that the estimate  $|1 - g_{ij}| < c(\omega) s^{-2}$  is valid for  $|s| \gg |k|$ , where c(0) = 0. Extracting the unity and using the representations [9]

$$J_0(z) = \frac{2}{\pi} \int_0^{\pi/2} \cos(z\sin\theta) d\theta, \quad J_1(z) = \frac{2}{\pi} \int_0^{\pi/2} \sin(z\sin\theta) \sin\theta d\theta$$

we reduce the system (2.3) to

$$\int_{0}^{\pi/2} G(r\sin\theta) d\theta = \beta f(r) - \alpha \int_{r}^{R} \frac{\varphi_{2}(t) dt}{\sqrt{t^{2} - r^{2}}} = g(r)$$

$$\int_{0}^{\pi/2} H(r\sin\theta) r\sin\theta d\theta = \alpha \int_{r}^{R} \frac{t\varphi_{1}(t) dt}{\sqrt{t^{2} - r^{2}}} - \alpha \int_{0}^{R} \varphi_{1}(t) dt = h(r)$$

$$G(r) = \varphi_{1}(r) - \frac{2}{\pi} \int_{0}^{R} K_{11}(t, r) \varphi_{1}(t) dt - \frac{2\alpha}{\pi} \int_{0}^{R} K_{12}(t, r) \varphi_{2}(t) dt$$

$$H(r) = \varphi_{2}(r) - \frac{2\alpha}{\pi} \int_{0}^{R} K_{21}(t, r) \varphi_{1}(t) dt - \frac{2}{\pi} \int_{0}^{R} K_{22}(t, r) \varphi_{2}(t) dt$$

$$K_{11} = \int_{0}^{\infty} (1 - g_{11}) \cos(ts) \cos(rs) ds, \quad K_{12} = \int_{0}^{\infty} (1 - g_{12}) \sin(ts) \cos(rs) ds$$

$$K_{21} = \int_{0}^{\infty} (1 - g_{21}) \cos(ts) \sin(rs) ds, \quad K_{22} = \int_{0}^{\infty} (1 - g_{22}) \sin(ts) \sin(rs) ds$$
(2.4)

The  $K_{ij}(t, r)$  are evidently continuous functions.

Let us assume that the shape of the stamp is given by a fourth power polynomial in r. If  $\varphi_1$  and  $\varphi_2$  are considered known, then each of the equations in the system (2.4) can be considered formally as a Schlömilch equation with a given right side continuously differentiable in the half-interval [0, R). It can be shown that the unique solution of the Schlomilch equation with such a right side continuous in [0, R) is given by the formula

$$G(r) = \frac{2}{\pi} \left[ g(0) + r \int_{0}^{\pi/2} g'(r\sin\theta) d\theta \right] =$$

$$\frac{2}{\pi} \left[ g(0) + r \frac{d}{dr} \int_{0}^{\pi/2} \frac{g(r\sin\theta) - g(0)}{\sin\theta} d\theta \right]$$
(2.5)

Substituting g(r) and h(r) successively into (2.5) and changing the order of integration with respect to t and  $\theta$ , we obtain

$$G(r) + \frac{\alpha}{\pi} \int_{0}^{R} \frac{2t}{t^{2} - r^{2}} \varphi_{2}(t) dt = \beta b(r)$$

$$H(r) - \frac{\alpha}{\pi} \int_{0}^{R} \frac{2r}{t^{2} - r^{2}} \varphi_{1}(t) dt = 0$$
(2.6)

where b(r) is the inversion of f(r) according to (2.5). The integrals are understood in the principal value sense. Let us note that  $\varphi_2(0) = 0$ ,  $K_{11}$  and  $K_{12}$  are even and  $K_{21}$ and  $K_{22}$  are odd in r. Continuing  $\varphi_1(t)$  evenly to the left and  $\varphi_2(t)$  oddly in a continuous way, we obtain a singular system with Cauchy kernel from (2.6)

$$\varphi_{1}(r) + \frac{\alpha}{\pi} \int_{-R}^{R} \frac{\varphi_{2}(t)}{t-r} dt - \frac{1}{\pi} \int_{-R}^{R} K_{11}(t,r) \varphi_{1}(t) dt -$$

$$\frac{\alpha}{\pi} \int_{-R}^{R} K_{12}(t,r) \varphi_{2}(t) dt = \beta b$$

$$\varphi_{2}(r) - \frac{\alpha}{\pi} \int_{-R}^{R} \frac{\varphi_{1}(t)}{t-r} dt - \frac{\alpha}{\pi} \int_{-R}^{R} K_{21}(t,r) \varphi_{1}(t) dt -$$

$$\frac{1}{\pi} \int_{-R}^{R} K_{22}(t,r) \varphi_{2}(t) dt = 0$$
(2.7)

**3.** Let  $\omega$  tend to zero. Then (1.2) and (1.3) go over into the known representation of the solution in terms of the biharmonic Love function. Because  $\lim K_{ij} = 0$  as  $\omega \to 0$  for all t and r, the regular part of the system (2.7) vanishes. Therefore, the static problem is described by the characteristic part of (2.7)

$$\varphi_{1}(r) + \frac{\alpha}{\pi} \int_{-R}^{R} \frac{\varphi_{2}(t)}{t-r} dt = \beta b$$

$$\varphi_{2}(r) - \frac{\alpha}{\pi} \int_{-R}^{R} \frac{\varphi_{1}(t)}{t-r} dt = 0$$
(3.1)

Let us introduce the analytic functions

$$\Phi_{1}(\zeta) = \frac{1}{2\pi i} \int_{-R}^{R} \frac{\phi_{1}(t)}{t-\zeta} dt, \qquad \Phi_{2}(\zeta) = \frac{1}{2\pi i} \int_{-R}^{R} \frac{\phi_{2}(t)}{t-\zeta} dt$$

By using the Sokhotskii-Plemelj formulas we reduce (3.1) to the two-dimensional problem of a conjugate with piecewise-constant coefficients

$$\Phi^{+} = G\Phi^{-} + g, \mid t \mid \leq R; \; \Phi^{+} = \Phi^{-}, \mid t \mid > R$$

Here

$$\Phi = \left\| \begin{array}{c} \Phi_1 \\ \Phi_2 \end{array} \right\|, \quad G = \left\| \begin{array}{c} \frac{1+\alpha^2}{1-\alpha^2} & \frac{-2i\alpha}{1-\alpha^2} \\ \frac{i2i\alpha}{1-\alpha^2} & \frac{1+\alpha^2}{1-\alpha^2} \end{array} \right\|, \quad g = \left\| \begin{array}{c} \frac{\beta b}{1-\alpha^2} \\ \frac{i\alpha\beta b}{1-\alpha^2} \end{array} \right\|$$

The eigenvalues G are distinct, hence there exists a matrix H such that  $H^{-1}GH$  is diagonal. Let us assume

$$\Phi = Hw, \qquad H = \left\| \begin{array}{cc} 1 & -i \\ -i & 1 \end{array} \right\|, \qquad w = \left\| \begin{array}{c} w_1 \\ w_2 \end{array} \right\|$$
$$w_1(\zeta) = \frac{1}{2\pi i} \int_{-R}^{R} \frac{\omega_1(t)}{t-\zeta} dt, \qquad w_2(\zeta) = \frac{1}{2\pi i} \int_{-R}^{R} \frac{\omega_2(t)}{t-\zeta} dt$$

Then the two-dimensional conjugate problem for  $\Phi$  reduces to two one-dimensional problems for w

$$w_1^{+} = \frac{1-\alpha}{1+\alpha} w_1^{-} + \frac{\beta b}{2(1+\alpha)}, \qquad w_2^{+} = \frac{1+\alpha}{1-\alpha} w_2^{-} + \frac{i\beta b}{2(1-\alpha)} \qquad (3.2)$$

Since b(r) is a polynomial, the solution of (3.2) can then be constructed explicitly.

As an illustration, let us consider a stamp with the flat base  $(f(r) = b_g)$ . Using the methods developed in [10], we obtain

$$w_1 = \frac{\beta b_0}{2\pi\alpha} [1 - X_1(\zeta)], \qquad w_2 = -\frac{i\beta b_0}{2\pi\alpha} [1 - X_2(\zeta)]$$
$$X_1 = \left(\frac{\zeta - R}{\zeta + R}\right)^{ia}, \qquad X_2 = \left(\frac{\zeta - R}{\zeta + R}\right)^{-ia}, \qquad a = \frac{1}{2\pi} \ln \frac{1 + \alpha}{1 - \alpha}$$

Evaluating the jumps, we find  $\omega_1, \omega_2, \phi_1, \phi_2$  by the Sokhotskii-Plemelj formulas

$$\omega_{1} = A x_{1} (t) = A e^{ia_{*}}, \quad \omega_{2} = iA x_{2} (t) = iA e^{-ia_{*}}$$
(3.3)  
$$\varphi_{1} = 2A \cos a_{*}, \quad \varphi_{2} = 2A \sin a_{*}$$
$$\left(A = \frac{\beta b_{0}}{\pi \sqrt{1-\alpha^{2}}}, \quad a_{*} = \frac{1}{2\pi} \ln \frac{1+\alpha}{1-\alpha} \ln \frac{R-t}{R+t}\right)$$

which agrees with the results in [3, 6].

4. Let us assume that  $\Lambda(x) \equiv M(x)$ . Using the exact solution (3.3), let us regularize the system (2.7).

To simplify the computations, let us reduce (2, 7) to the system

$$\omega_{1}(r) + \frac{\alpha}{\pi i} \int_{-R}^{R} \frac{\omega_{1}(t)}{t-r} dt = \frac{\beta b_{0}}{\pi} + \frac{1}{2\pi} \int_{-R}^{R} H_{11}(t,r) \omega_{1}(t) dt +$$

$$\frac{i}{2\pi} \int_{-R}^{R} H_{12}(t,r) \omega_{2}(t) dt$$
(4.1)

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$$\omega_{2}(r) - \frac{\sigma}{\pi i} \int_{-R}^{R} \frac{\omega_{2}(t)}{t-r} dt = \frac{i\beta b}{\pi} + \frac{i}{2\pi} \int_{-R}^{R} H_{21}(t,r) \omega_{1}(t) dt + \frac{1}{2\pi} \int_{-R}^{R} H_{22}(t,r) \omega_{2}(t) dt$$

by means of the substitution  $\varphi = H_{00}$ . The kernels  $H_{ij}$  are connected with the  $K_{ij}$ by the relationships

$$H_{11} = K_{11} + K_{22} + i\alpha (K_{21} - K_{12})$$

$$H_{12} = K_{22} - K_{11} - i\alpha (K_{12} + K_{21})$$

$$H_{21} = K_{11} - K_{22} - i\alpha (K_{12} + K_{21})$$

$$H_{22} = K_{11} + K_{22} - i\alpha (K_{21} - K_{12})$$
(4.2)

Regularizing (4.1) in conformity with Vekua [1], we obtain

$$\omega_{1}(r) = Ax_{1}(r) + \frac{1}{2\pi} \int_{-R}^{R} h_{11}(t, r) \omega_{1}(t) dt + \frac{i}{2\pi} \int_{-R}^{R} h_{12}(t, r) \omega_{2}(t) dt \quad (4.3)$$
  
$$\omega_{2}(r) = iAx_{2}(r) + \frac{i}{2\pi} \int_{-R}^{R} h_{21}(t, r) \omega_{1}(t) dt + \frac{1}{2\pi} \int_{-R}^{R} h_{22}(t, r) \omega_{2}(t) dt \quad (4.3)$$
  
$$(h_{ij} = w_{ij}^{+} - w_{ij}^{-})$$

The functions  $w_{ij}$  are introduced by means of the relationships

$$w_{1n} = \frac{X_1(\zeta)}{2\pi i} \int_{-R}^{R} \frac{H_{1n}(t,\tau)}{(1+\alpha) X_1^+(\tau)} \frac{d\tau}{\tau-\zeta}$$

$$w_{2n} = \frac{X_2(\zeta)}{2\pi i} \int_{-R}^{R} \frac{H_{2n}(t,\tau)}{(1-\alpha) X_2^+(\tau)} \frac{d\tau}{\tau-\zeta}$$

$$(4.4)$$

$$(4.4)$$

The system (4.3) is a quasi-regular system of Fredholm equations of the second kind.

Let us construct the solution of (4.3) under the assumption that the parameter  $\theta = kR$  is small. It can be shown that the kernels  $K_{12}$ ,  $K_{21}$ ,  $K_{22}$  are of higher order compared to  $\theta$ . To estimate  $K_{11}$ , let us use the following reasoning. If

Re  $(s^2 - k_{1,2}^2)^{1/2} \ge 0$ , Re  $(s^2 - \bar{k}_{1,2}^2)^{1/2} \ge 0$ ,  $\frac{1}{2} \operatorname{Po}(s^2 - \bar{k}_{1,2})^{1/2} \ge 0$ ,  $\frac{1}{2} \operatorname{Po}(\bar{k} - \bar{k}_{1,2})^{1/2} \ge 0$ ,

then

$$\operatorname{Re} K_{11} = \frac{1}{4} \operatorname{Re} \int_{0}^{\infty} [2 - g_{11}(k_1, k_2, s) - g_{11}(\bar{k}_1, \bar{k}_2, s)] (e^{i|t-r|s} + e^{i|t+r|s}) ds$$

In the first quadrant the integrand has a first order pole and the branch point  $\overline{k_1}$ ,  $\overline{k_2}$ . It takes on real values on the imaginary axis. Taking the contour of integration indicated in Fig. 1 and using the estimate  $|1 - g_{11}| < c (\omega) s^{-2}$ , we obtain that the real part of the kernel  $K_{11}$  equals the real part of the sum of the residue multiplied by  $2\pi i$  and the integrals over the edges of the slit. Retaining first order terms in this sum, we obtain

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$$\operatorname{Re} K_{11} = \frac{1}{2R} \beta h(\alpha) \operatorname{Re}(-i\overline{\vartheta}), \quad h(\alpha) = \pi \operatorname{res}_{\varepsilon}\left(\frac{\overline{k}ps}{D}\right) + \int_{0}^{\sqrt{\alpha}} \frac{\xi \sqrt{\alpha - \overline{\xi}^{2}} d\xi}{\xi^{2} \sqrt{(\alpha - \xi^{2})(1 - \xi^{2})} + (\xi^{2} - \frac{1}{2})^{2}} + \int_{\sqrt{\alpha}}^{1} \frac{\xi^{3}(\xi^{2} - \alpha) \sqrt{1 - \xi^{2}} d\xi}{\xi^{4}(\xi^{2} - \alpha)(1 - \xi^{2}) + (\xi^{2} - \frac{1}{2})^{2}} d\xi$$

We obtain analogously

$$\operatorname{Im} K_{11} = \frac{1}{2R} \,\beta h(\alpha) \,\operatorname{Im} (i\bar{\theta})$$

so that

$$K_{11} = \frac{1}{2R} \,\beta h\left(\alpha\right) i \theta$$

Substituting the estimate found into (4.2) and (4.4), we obtain

$$h_{11} = -h_{12} = \frac{\beta h(\alpha) i\theta}{2R \sqrt{1-\alpha^2}} x_1(r) \quad (4.5)$$

$$h_{21} = h_{22} = \frac{\beta h(\alpha) i\theta}{2R \sqrt{1-\alpha^2}} x_2(r)$$

Let us apply successive approximations to (4.3). Let us take the static solution (3.3) as the first approximation

$$\omega_{1}(r) = A x_{1}(r), \ \omega_{2}(r) = i A x_{2}(r)$$

$$\omega_1(r) = A_* x_1(r), \ \omega_2(r) = i A_* x_2(r) \quad (A_* = 1 + a\gamma h(\alpha) i\theta)$$

In a first approximation the solution of (2.7) has the form

$$\varphi_1(r) = 2A_* \cos\left(a \ln \frac{R-r}{R+r}\right), \quad \varphi_2(r) = 2A_* \sin\left(a \ln \frac{R-r}{R+r}\right)$$

5. We find the reaction of the half-space (in the static case  $\theta = 0$ ) by the methods of integrating multivalued functions

$$P = 2\pi \int_{0}^{R} \sigma_{z}(r,0) r dr = 2\pi \mu_{*} \int_{-R}^{R} \varphi_{1}(t) dt =$$
  
$$4(\lambda_{*} + \mu_{*}) [1 + a\gamma h(\alpha) i\theta] \ln \left(\frac{\lambda_{*} + 3\mu_{*}}{\lambda_{*} + \mu_{*}}\right) b_{0}R$$

Let us investigate the behavior of the stresses at the edge of the stamp. Let us note that because of the properties of  $\varphi_1(t)$  and  $\varphi_2(t)$  the relationships (2.2) can be represented as

$$\frac{1}{2\mu_{*}}\sigma_{z} = \frac{\varphi_{1}(r)}{\sqrt{R^{2} - r^{2}}} - \int_{r}^{R} \frac{t \left[\varphi_{1}(t) - \varphi_{1}(r)\right]}{\left(t^{2} - r^{2}\right)^{s_{2}}} dt$$
$$\frac{1}{2\mu_{*}}\tau_{rz} = \frac{\varphi_{2}(r)}{\sqrt{R^{2} - r^{2}}} - \int_{r}^{R} \frac{r \varphi_{2}(t) - t\varphi_{2}(r)}{\left(t^{2} - r^{2}\right)^{s_{2}}} dt$$



Fig. 1

We set  $t = R \operatorname{th} \frac{1}{2} \xi$ ,  $r = R \operatorname{th} \frac{1}{2} x$ , so that

$$\begin{aligned} \frac{1}{2\mu_*} \sigma_z &= 2A \operatorname{ch} \frac{x}{2} \left[ \cos\left(ax\right) + \varphi(x) \right], \quad \varphi(x) = \int_x^\infty \frac{\psi_1\left(\xi, x\right)}{\psi_2\left(\xi, x\right)} d\xi \\ \psi_1 &= \operatorname{th} \frac{\xi}{2} \sin\left(a \frac{\xi - x}{2}\right) \sin\left(a \frac{\xi + x}{2}\right) \left(c \frac{x}{2}\right)^{1/2} \\ \psi_2 &= \left(\operatorname{th} \frac{x}{2} + \operatorname{th} \frac{\xi}{2}\right)^{3/2} \left(\operatorname{sh} \frac{\xi - x}{2}\right)^{3/2} \left(\operatorname{ch} \frac{\xi}{2}\right)^{1/2} \\ \operatorname{stimates} & \left| \frac{\psi_1}{\psi_2} \right| < \frac{|a|}{2\sqrt{2}} \left(\operatorname{th} \frac{x}{2}\right)^{-3/2} \left(\operatorname{sh} \frac{\xi - x}{2}\right)^{-1/2} \\ |\varphi(x)| < \frac{|a|}{\sqrt{2}} \left(\operatorname{th} \frac{x}{2}\right)^{-3/2} \int_0^\infty (\operatorname{sh} u)^{-1/2} du < \frac{2\ln 3}{\pi} \left(\operatorname{th} \frac{x}{2}\right)^{-3/2} \end{aligned}$$

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are valid, hence  $\varphi(x)$  is a continuous function and  $|\varphi(x)| < 1$  starting with some x. Therefore, the equation  $\cos(ax) + \varphi(x) = 0$  has an infinite number of zeros and the stress  $\sigma_z$  oscillates at the edge of the stamp. The oscillation of  $\tau_{rz}$  is proved analogously. The same phenomenon evidently holds also in dynamics, at least for low vibration frequencies.

It should be noted that the method developed above is applicable for arbitrary  $\Lambda$  and M. However, the structure of  $h(\alpha)$  is considerably more complex in the general case. In the particular case of an elastic medium  $\alpha$  and  $\theta$  take on only real positive values.

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## ON THE PROBLEM OF THE RELATIONSHIP BETWEEN

## THE SCHWARZSCHILD AND TOLMAN METRICS

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The problem of the relationship between the Schwarzschild and Tolman metrics has occupied the attention of many workers. Although the solutions given in [1-3] satisfy the equations of the general relativity theory (OTO) (\*), they contradict the correspondence principle. This means that for  $G \rightarrow 0$ , the interval is not transformed into the interval of the special relativity theory (CTO) (\*), while for  $c \rightarrow \infty$ , the solutions do not become Newtonian. This is apparently caused by the unfortunate choice of the coordinates in the Tolman frame of reference. Papers [4, 5] illustrate particular cases of a correct passage from one metric to the other.

In the present paper a general method of obtaining solutions is proposed in which the passage from one frame of reference to the other satisfies the correspondence principle.

The intervals in the co-moving frame of reference and in the central frame of reference are, respectively,

$$- ds^{2} = - c^{2} d\tau^{2} + e^{\omega} dR^{2} + r^{2} d\Omega^{2}$$
<sup>(1)</sup>

$$- ds^{2} = -e^{\nu}c^{2}dt^{2} + e^{\lambda}dr^{2} + r^{2}d\Omega^{2}$$

$$(d\Omega^{2} = d\theta^{2} + \sin^{2}\theta d\varphi^{2})$$
(2)

Since  $r = r(c\tau, R)$  and  $ct = ct(c\tau, R)$ , we have

$$dr = r^{*}cd\tau + r'dR, \ cdt = ct^{*}cd\tau + ct'dR$$
  
(r' =  $\partial r/c\partial \tau, \ r' = \partial r / \partial R, \ ct' = c\partial t / c\partial \tau, \ ct' = c\partial t / \partial R$ )

Substituting these differentials into (2), equating the coefficients accompanying  $c^2 d\tau^2$ and  $dR^2$  and remembering that the coefficient of  $2cd\tau dR$  is zero, we obtain

$$e^{\nu}c^{2}t^{2} - r^{2}e^{\lambda} = 1, \quad e^{\lambda}r'^{2} - c^{2}t'^{2}e^{\nu} = e^{\omega}, \quad e^{\lambda}r'r' - ct'ct'e^{\nu} = 0$$
 (3)

from which, eliminating  $e^{\lambda}$  and  $e^{\nu}$ , we have

$$e^{\lambda} = e^{\omega} / (r'^{2} - r'^{2}e^{\omega}), \ e^{\nu} = r'^{2} / [c^{2}t'^{2} (r'^{2} - r'^{2}e^{\omega})]$$
(4)  
$$(e^{\omega}ct'r' - ct'r') (ct'r' - ct'r') = 0$$

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<sup>\*)</sup> Editors note. The abbreviations (OTO) and (CTO) are used in the relevant Soviet literature and stand for "general relativity theory" and "special relativity theory", respectively.