## AXISYMMETRIC DYNAMIC CONTACT PROBLEM FOR A VISCOELASTIC

## HALF-SPACE IN THE PRESENCE OF ADHESION UNDER THE STAMP

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The steady vibrations of a rigid stamp of circular planform adhering to the surface of a viscoelastic half-space subjected to a harmonic axial force are considered. There are no forces outside the region of contact.

The system of dual integral equations constructed by using the Hankel transform is reduced to a system of singular integral equations regularized according to Vekua [1]. An approximate solution, valid for small vibrations frequencies, is found. Oscillatory behavior of the stresses is proved. Abramov [2] detected a similar fact in the plane case.

The static problem for an elastic medium has been examined by a number of authors $[3-6]$. None of the listed papers detected the oscillatory behavior of the stresses at the edge of the stamp.

1. The complex amplitudes of the displacements of a viscoelastic medium in the presence of axial symmetry satisfy the system of equations

$$
\begin{align*}
& \left(\lambda_{*}+2 \mu_{*}\right) \frac{\partial \Delta}{\partial r}+\mu_{*} \frac{\partial}{\partial z}\left(2 \omega_{\varphi}\right)=-\rho \omega^{2} u_{r}  \tag{1.1}\\
& \left(\lambda_{*}+2 \mu_{*}\right) \frac{\partial \Delta}{\partial z}-\mu_{*} \frac{1}{r} \frac{\partial}{\partial r}\left(2 r \omega_{\varphi}\right)=-\rho \omega^{2} u_{z} \\
& \Delta=\frac{1}{r} \frac{\partial}{\partial r}\left(r u_{r}\right)+\frac{\partial}{\partial z} u_{z}, \quad 2 \omega_{\varphi}=\frac{\partial}{\partial z} u_{r}-\frac{\partial}{\partial r} u_{z} \\
& \lambda_{*}=\lambda\left[1-\int_{0}^{\infty} \Lambda(x) e^{-i \omega x} d x\right], \quad \mu_{*}=\mu\left[1-\int_{0}^{\infty} M(x) e^{-i \omega x} d x\right]
\end{align*}
$$

Here $\rho$ is the density of the medium, $\omega$ is the vibrations frequency, $\lambda_{*}$ and $\mu_{*}$ are the complex moduli.

Let us assume that the medium occupies the half-space $z \leqslant 0$. By using the Hankel transform, we obtain the amplitudes of the displacements in the following form from (1.1):

$$
\begin{align*}
& u_{z}=\int_{0}^{\infty}\left[p e^{p z} A(\omega, s)-\Theta\left(s e^{q z}-p e^{p z}\right) s B(\omega, s)\right] J_{0}(r s) d s  \tag{1.2}\\
& u_{r}=-\int_{0}^{\infty} s\left[e^{p z} A(\omega, s)+\Theta\left(s e^{p z}-q e^{q z}\right) B(\omega, s)\right] J_{1}(r s) d s \\
& p=\left(s^{2}-k_{1}^{2}\right)^{1 / 2}, \quad q=\left(s^{2}-{k_{2}}^{2}\right)^{1 / 2}, \quad \Theta=\left(k_{2}^{2}-k_{1}^{2}\right)^{-1} \\
& k_{1}^{2}=\frac{\rho \omega^{2}}{\lambda_{*}+2 \mu_{*}}, \quad k_{2}{ }^{2}=\frac{\rho \omega^{2}}{\mu_{*}}, \quad \operatorname{Re} k_{1} \geqslant 0, \quad \operatorname{Re} k_{2} \geqslant 0
\end{align*}
$$

Here $A(\omega, s)$ and $B(\omega, s)$ are unknown functions and $p$ and $q$ are branches of the roots which satisfy the conditions $\operatorname{Re} p \geqslant 0, \operatorname{Re} q \geqslant 0$. The stress amplitudes are obtained from (1.2) as

$$
\begin{align*}
& \frac{1}{2 \mu_{*}} \sigma_{z}=\int_{0}^{\infty}\left[x e^{p z} A-\Theta\left(q s e^{q z}-\chi e^{p z}\right) s B\right] J_{0}(r s) d s  \tag{1.3}\\
& \frac{1}{2 \mu_{*}} \tau_{r z}=-\int_{0}^{\infty} s\left[p e^{p z} A+\Theta\left(p s e^{p z}-x e^{q z}\right) B\right] J_{1}(r s) d s \\
& \left(\chi=s^{2}-{k_{2}}^{2} / 2\right)
\end{align*}
$$

The boundary conditions on the surface $z=0$

$$
u_{z}=f(r), \quad u_{r}=0 \quad \text { for } r<R ; \quad \sigma_{z}=\tau_{r z}=0 \quad \text { for } \quad r \geqslant R
$$

should be used to determine $A$ and $B$. Letting $z$ tend to 0 , we obtain a system of dual equations from (1.2) and (1.3)

$$
\begin{array}{ll}
\int_{0}^{\infty}[p A-\Theta(s-p) s B] J_{0}(r s) d s=f(r) & \\
\int_{0}^{\infty} s[A+\Theta(s-q) B] J_{1}(r s) d s=0 & \\
\int_{0}^{\infty}[\varkappa A-\Theta(q s-\chi) s B] J_{0}(r s) d s=0 & \\
\int_{0}^{\infty} s[p A+\Theta(p s-\chi) B] J_{1}(r s) d s=0 &  \tag{1.5}\\
\end{array}
$$

2. Analogously to the method developed in [7], let us assume

$$
\begin{align*}
& x A-\Theta(q s-x) s B=s \int_{0}^{R} \varphi_{1}(t) \cos (t s) d t  \tag{2.1}\\
& p A+\Theta(p s-x) B=-\int_{0}^{R} \varphi_{2}(t) \sin (t s) d t
\end{align*}
$$

The relationships (2.1) are a linear system of equations in $A$ and $B$. The functions $\varphi_{1}(t)$ and $\varphi_{2}(t)$ are assumed bounded and continuously differentiable in the halfinterval $[0, R)$. Substituting (2.1) into (1.3) and using the formulas for differentiation of the Bessel functions, we obtain that at $z=0$

$$
\begin{aligned}
& \frac{1}{2 \mu_{*}} \sigma_{z}=\frac{1}{r} \frac{d}{d r} \int_{0}^{R} \varphi_{1}(t)\left[\int_{0}^{\infty} r J_{1}(r s) \cos (t s) d s\right] d t \\
& \frac{1}{2 \mu_{*}} \tau_{r z}=-\frac{d}{d r} \int_{0}^{R} \varphi_{2}(t)\left[\int_{0}^{\infty} J_{0}(r s) \sin (t s) d s\right] d t
\end{aligned}
$$

From the properties of the Weber-Schafheitlin integrals [8] as well as the properties of $\varphi_{1}(t)$ and $\varphi_{2}(t)$ there results that $\sigma_{z}=\tau_{r \cdot z}=0$ for $r \geqslant R$. The relationships

$$
\begin{equation*}
\frac{1}{2 \mu_{*}} \sigma_{z}=-\frac{1}{r} \frac{d}{d r} \int_{r}^{R} \frac{t \varphi_{1}(t) d t}{\sqrt{t^{2}-r^{2}}}, \quad \frac{1}{2 \mu_{*}} \tau_{r z}--\frac{d}{d r} \int_{r}^{R} \frac{\varphi_{2}(t) d t}{\sqrt{t^{2}-r^{2}}} \tag{2.2}
\end{equation*}
$$

hold under the stamp. Eliminating $A$ and $B$ from (1.4) and (2.1), we obtain the system

$$
\begin{align*}
& \int_{0}^{\infty} \int_{0}^{R}\left[g_{11} \varphi_{1}(t) \cos (t s)+\alpha g_{12} \varphi_{2}(t) \sin (t s)\right] J_{0}(r s) d t d s=\beta f(r)  \tag{2.3}\\
& \int_{0}^{\infty} \int_{0}^{R}\left[\alpha g_{21} \varphi_{1}(t) \cos (t s)+g_{22} \varphi_{2}(t) \sin (t s)\right] J_{1}(r s) d t d s=0 \\
& g_{11}\left(k_{1}, k_{2}, s\right)=\frac{\beta k^{2} p s}{2 D}, \quad g_{22}\left(k_{1}, k_{2}, s\right)=\frac{\beta k^{2} q s}{2 D} \\
& g_{12}\left(k_{1}, k_{2}, s\right)=g_{21}\left(k_{1}, k_{2}, s\right)=-\frac{\gamma s^{2}(p q-x)}{\vdots D} \\
& \left(\alpha=\frac{\mu_{*}}{\lambda_{*}+2 \mu_{*}}, \beta=\frac{\lambda_{*}+\mu_{*}}{\lambda_{*}+2 \mu_{*}}, \gamma=\frac{\beta}{\alpha}, k=k_{2}, \quad D=p q s^{2}-x^{2}\right)
\end{align*}
$$

An analysis of the behavior of $g_{i j}$ at infinity shows that the estimate $\left|1-g_{i j}\right|<$ $c(\omega) s^{-2}$ is valid for $|s| \gg|k|$, where $c(0)=0$. Extracting the unity and using the representations [9]

$$
J_{0}(z)=\frac{2}{\pi} \int_{0}^{\pi / 2} \cos (z \sin \theta) d \theta, \quad J_{1}(z)=\frac{2}{\pi} \int_{0}^{\pi / 2} \sin (z \sin \theta) \sin \theta d \theta
$$

we reduce the system (2.3) to

$$
\begin{align*}
& \int_{0}^{\pi / 2} G(r \sin \theta) d \theta=\beta f(r)-\alpha \int_{r}^{R} \frac{\varphi_{2}(t) d t}{\sqrt{t^{2}-r^{2}}}=g(r)  \tag{2.4}\\
& \int_{0}^{\pi / 2} H(r \sin \theta) r \sin \theta d \theta=\alpha \int_{r}^{R} \frac{t \varphi_{1}(t) d t}{\sqrt{t^{2}-r^{2}}}-\alpha \int_{0}^{R} \varphi_{1}(t) d t=h(r) \\
& G(r)=\varphi_{1}(r)-\frac{2}{\pi} \int_{0}^{R} K_{11}(t, r) \varphi_{1}(t) d t-\frac{2 \alpha}{\pi} \int_{0}^{R} K_{12}(t, r) \varphi_{2}(t) d t \\
& H(r)=\varphi_{2}(r)-\frac{2 \alpha}{\pi} \int_{0}^{R} K_{21}(t, r) \varphi_{1}(t) d t-\frac{2}{\pi} \int_{0}^{R} K_{22}(t, r) \varphi_{2}(t) d t \\
& K_{11}=\int_{0}^{\infty}\left(1-g_{11}\right) \cos (t s) \cos (r s) d s, \quad K_{12}=\int_{0}^{\infty}\left(1-g_{12}\right) \sin (t s) \cos (r s) d s \\
& K_{21}=\int_{0}^{\infty}\left(1-g_{21}\right) \cos (t s) \sin (r s) d s, \quad K_{22}-\int_{0}^{\infty}\left(1-g_{22}\right) \sin (t s) \sin (r s) d s
\end{align*}
$$

The $K_{i j}(t, r)$ are evidently continuous functions.
Let us assume that the shape of the stamp is given by a fourth power polynomial in $r$. If $\varphi_{1}$ and $\varphi_{2}$ are considered known, then each of the equations in the system (2.4) can be considered formally as a Schlömilch equation with a given right side continuously
differentiable in the half-interval $[0, R)$. It can be shown that the unique solution of the Schlomilch equation with such a right side continuous in $[0, R)$ is given by the formula

$$
\begin{align*}
& G(r)=\frac{2}{\pi}\left[g(0)+r \int_{0}^{\pi} g^{\prime}(r \sin \theta) d \theta\right]=  \tag{2.5}\\
& \frac{2}{\pi}\left[g(0)+r \frac{d}{d r} \int_{0}^{\pi / 2} \frac{g(r \sin \theta)-g(0)}{\sin \theta} d \theta\right]
\end{align*}
$$

Substituting $g(r)$ and $h(r)$ successively into (2.5) and changing the order of integration with respect to $t$ and $\theta$, we obtain

$$
\begin{align*}
& G(r)+\frac{\alpha}{\pi} \int_{0}^{R} \frac{2 t}{t^{2}-r^{2}} \varphi_{2}(t) d t=\beta b(r)  \tag{2.6}\\
& H(r)-\frac{\alpha}{\pi} \int_{0}^{R} \frac{2 r}{t^{2}-r^{2}} \varphi_{1}(t) d t=0
\end{align*}
$$

where $b(r)$ is the inversion of $f(r)$ according to (2.5). The integrals are understood in the principal value sense. Let us note that $\varphi_{2}(0)=0, K_{11}$ and $K_{12}$ are even and $K_{21}$ and $K_{22}$ are odd in $r$. Continuing $\varphi_{1}(t)$ evenly to the left and $\varphi_{2}(t)$ oddly in a continuous way, we obtain a singular system with Cauchy kernel from (2.6)

$$
\begin{align*}
& \varphi_{1}(r)+\frac{\alpha}{\pi} \int_{-R}^{R} \frac{\varphi_{2}(t)}{t-r} d t-\frac{1}{\pi} \int_{-R}^{R} K_{11}(t, r) \varphi_{1}(t) d t-  \tag{2.7}\\
& \quad \frac{\alpha}{\pi} \int_{-R}^{R} K_{12}(t, r) \varphi_{2}(t) d t=\beta b \\
& \varphi_{2}(r)-\frac{\alpha}{\pi} \int_{-R}^{R} \frac{\varphi_{1}(t)}{t-r} d t-\frac{\alpha}{\pi} \int_{-R}^{R} K_{21}(t, r) \varphi_{1}(t) d t- \\
& \cdot \frac{1}{\pi} \int_{-R}^{R} K_{22}(t, r) \varphi_{2}(t) d t=0
\end{align*}
$$

3. Let $\omega$ tend to zero. Then (1.2) and (1.3) go over into the known representation of the solution in terms of the biharmonic Love function. Because $\lim K_{i j}=0$ as $\omega \rightarrow 0$ for all $t$ and $r$, the regular part of the system (2.7) vanishes. Therefore, the static problem is described by the characteristic part of (2.7)

$$
\begin{align*}
& \varphi_{1}(r)-+\frac{\alpha}{\pi} \int_{-R}^{R} \frac{\varphi_{2}(t)}{t-r} d t=\beta b  \tag{3.1}\\
& \varphi_{2}(r)-\frac{\alpha}{\pi} \int_{-R}^{R} \frac{\varphi_{1}(t)}{t-r} d t=0
\end{align*}
$$

Let us introduce the analytic functions

$$
\Phi_{1}(\zeta)=\frac{1}{2 \pi i} \int_{-R}^{R} \frac{\varphi_{1}(t)}{t-\zeta} d t, \quad \Phi_{2}(\zeta)=\frac{1}{2 \pi i} \int_{-R}^{R} \frac{\varphi_{2}(t)}{t-\zeta} d t
$$

By using the Sokhotskii-Plemelj formulas we reduce (3.1) to the two-dimensional problem of a conjugate with piecewise-constant coefficients

$$
\Phi^{+}=G \Phi^{-}+g,|t| \leqslant R ; \Phi^{+}=\Phi^{-},|t|>R
$$

Here

$$
\Phi=\left\|\begin{array}{l}
\Phi_{1} \\
\Phi_{2}
\end{array}\right\|, \quad G-\left\|\begin{array}{cc}
\frac{1+\alpha^{2}}{1-\alpha^{2}} & \frac{-2 i \alpha}{1-\alpha^{2}} \\
\frac{i 2 i \alpha}{1-\alpha^{2}} & \frac{1+\alpha^{2}}{1-\alpha^{2}}
\end{array}\right\|, \quad g=\left\|\frac{\beta b}{1-\alpha^{2}}\right\| \frac{i \alpha \beta b}{1-\alpha^{2}} \|
$$

The eigenvalues $G$ are distinct, hence there exists a matrix $H$ such that $H^{-1} G H$ is diagonal. Let us assume

$$
\begin{aligned}
& \Phi=H w, \quad H=\left\|\begin{array}{rr}
1 & -i \\
-i & 1
\end{array}\right\|, \quad w=\left\|\begin{array}{l}
w_{1} \\
w_{2}
\end{array}\right\| \\
& w_{1}(\zeta)=\frac{1}{2 \pi i} \int_{-R}^{R} \frac{\omega_{1}(t)}{t-\zeta} d t, \quad w_{2}(\zeta)=\frac{1}{2 \pi i} \int_{-R}^{R} \frac{\omega_{2}(t)}{t-\zeta} d t
\end{aligned}
$$

Then the two-dimensional conjugate problem for $\Phi$ reduces to two one-dimensional problems for $w$

$$
\begin{equation*}
w_{1}^{+}=\frac{1-\alpha}{1+\alpha} w_{1}^{-}+\frac{\beta b}{2(1+\alpha)}, \quad w_{2}^{+}=\frac{1+\alpha}{1-\alpha} w_{2}^{-}+\frac{i \beta b}{2(1-\alpha)} \tag{3.2}
\end{equation*}
$$

Since $b(r)$ is a polynomial, the solution of (3.2) can then be constructed explicitly.
As an illustration, let us consider a stamp with the flat base $\left(f(r)=b_{0}\right)$. Using the methods developed in [10], we obtain

$$
\begin{aligned}
& w_{1}=\frac{\beta b_{0}}{2 \pi \alpha}\left[1-X_{1}(\zeta)\right], \quad w_{2}=-\frac{i \beta b_{0}}{2 \pi \alpha}\left[1-X_{2}(\zeta)\right] \\
& X_{1}=\left(\frac{\zeta-R}{\zeta+R}\right)^{i a}, \quad X_{2}=\left(\frac{\zeta-R}{\zeta+R}\right)^{-i a}, \quad a=\frac{1}{2 \pi} \ln \frac{1+\alpha}{1-\alpha}
\end{aligned}
$$

Evaluating the jumps, we find $\omega_{1}, \omega_{2}, \varphi_{1}, \varphi_{2}$ by the Sokhotskii-Plemelj formulas

$$
\begin{align*}
& \omega_{1}=A x_{1}(t)=A e^{i a_{*}}, \omega_{2}=i A x_{2}(t)=i A e^{-i a_{*}}  \tag{3.3}\\
& \varphi_{1}=2 A \cos a_{*}, \quad \varphi_{2}=2 A \sin a_{*} \\
& \left(A=\frac{\beta b_{0}}{\pi \sqrt{1-\alpha^{2}}}, \quad a_{*}=\frac{1}{2 \pi} \ln \frac{1+\alpha}{1-\alpha} \ln \frac{R-t}{R+t}\right)
\end{align*}
$$

which agrees with the results in $[3,6]$.
4. Let us assume that $\Lambda(x) \equiv M(x)$. Using the exact solution (3.3), let us regularize the system (2.7).

To simplify the computations, let us reduce (2.7) to the system

$$
\begin{align*}
& \omega_{1}(r)+\frac{\alpha}{\pi i} \int_{-R}^{R} \frac{\omega_{1}(t)}{t-r} d t=\frac{\beta b_{0}}{\pi}+\frac{1}{2 \pi} \int_{-R}^{R} H_{11}(t, r) \omega_{1}(t) d t+  \tag{4.1}\\
& \quad \frac{i}{2 \pi} \int_{-R}^{R} H_{12}(t, r) \omega_{2}(t) d t
\end{align*}
$$

$$
\begin{aligned}
& \omega_{2}(r)-\frac{\alpha}{\pi i} \int_{-R}^{R} \frac{\omega_{2}(t)}{t-r} d t=\frac{i \beta b_{1}}{\pi}+\frac{i}{2 \pi} \int_{-R}^{R} H_{21}(t, r) \omega_{1}(t) d t+ \\
& \quad \frac{1}{2 \pi} \int_{-R}^{R} H_{22}(t, r) \omega_{2}(t) d t
\end{aligned}
$$

by means of the substitution $\varphi=H \omega$. The kernels $H_{i j}$ are connected with the $K_{i j}$ by the relationships

$$
\begin{align*}
& H_{11}=K_{11}+K_{22}+i \alpha\left(K_{21}-K_{12}\right)  \tag{4.2}\\
& H_{12}=K_{22}-K_{11}-i \alpha\left(K_{12}+K_{21}\right) \\
& H_{21}=K_{11}-K_{22}-i \alpha\left(K_{12}+K_{21}\right) \\
& H_{22}=K_{11}+K_{22}-i \alpha\left(K_{21}-K_{12}\right)
\end{align*}
$$

Regularizing (4.1) in conformity with Vekua [1], we obtain

$$
\begin{align*}
& \omega_{1}(r)=A x_{1}(r)+\frac{1}{2 \pi} \int_{-R}^{R} h_{11}(t, r) \omega_{1}(t) d t+\frac{i}{2 \pi} \int_{-R}^{R} h_{12}(t, r) \omega_{2}(t) d t  \tag{4.3}\\
& \omega_{2}(r)=i A x_{2}(r)+\frac{i}{2 \pi} \int_{-R}^{R} h_{21}(t, r) \omega_{1}(t) d t+\frac{1}{2 \pi} \int_{-R}^{R} h_{22}(t, r) \omega_{2}(t) d t \\
& \left(h_{i j}=w_{i j^{+}}{ }^{+}-w_{i j^{-}}\right)
\end{align*}
$$

The functions $w_{i j}$ are introduced by means of the relationships

$$
\begin{align*}
& w_{1 n}=\frac{X_{1}(\zeta)}{2 \pi i} \int_{-R}^{R} \frac{H_{1 n}(t, \tau)}{(1+\alpha) X_{1}+(\tau)} \frac{d \tau}{\tau-\zeta}  \tag{4.4}\\
& w_{2 n}=\frac{X_{2}(\zeta)}{2 \pi i} \int_{-R}^{R} \frac{H_{2 n}(t, \tau)}{(1-\alpha) X_{2^{+}(\tau)}} \frac{d \tau}{\tau-\zeta} \\
& (n=1,2)
\end{align*}
$$

The system (4.3) is a quasi-regular system of Fredholm equations of the second kind.
Let us construct the solution of (4.3) under the assumption that the parameter $\theta=$ $k R$ is small, It can be shown that the kernels $K_{12}, K_{21}, K_{22}$ are of higher order compared to $\theta$. To estimate $K_{11}$, let us use the following reasoning. If

$$
\operatorname{Re}\left(s^{2}-k_{1,2}^{2}\right)^{1 / 2} \geqslant 0, \operatorname{Re}\left(s^{2}-\bar{k}_{1,2}^{2}\right)^{1 / 2} \geqslant 0
$$

then

$$
\operatorname{Re} K_{11}=\frac{1}{4} \operatorname{Re} \int_{0}^{\infty}\left[2-g_{11}\left(k_{1}, k_{2}, s\right)-g_{11}\left(\bar{k}_{1}, \bar{k}_{2}, s\right)\right]\left(e^{i|t-r| s}+e^{i l t+r \mid s}\right) d s
$$

In the first quadrant the integrand has a first order pole and the branch point $\bar{k}_{1}, \bar{k}_{2}$. It takes on real values on the imaginary axis. Taking the contour of integration indicated in Fig. 1 and using the estimate $\left|1-g_{11}\right|<c(\omega) s^{-2}$, we obtain that the real part of the kernel $K_{11}$ equals the real part of the sum of the residue multiplied by $2 \pi i$ and the integrals over the edges of the slit. Retaining first order terms in this sum, we obtain
$\operatorname{Re} K_{11}-\frac{1}{2 R} \beta h(\alpha) \operatorname{Re}(-i \overrightarrow{9}), \quad h(\alpha)=\pi \operatorname{res}_{\varepsilon}\left(\frac{\bar{k} p s}{D}\right)+$

$$
\left.\int_{0}^{\sqrt{\alpha}} \frac{\xi \sqrt{\alpha-\xi^{2}} d \xi}{\xi^{2} \sqrt{\left(\alpha-\xi^{2}\right)\left(1-\xi^{2}\right)}+\left(\xi^{2}-1 / 2\right)^{2}}+\int_{\sqrt{\alpha}}^{1} \frac{\xi^{3}\left(\xi^{2}-\alpha\right) \sqrt{1-\xi^{2}} d \xi}{\left.\xi^{4}-\alpha\right)\left(1-\xi^{2}\right)+\left(\xi^{2}-1 / 2\right.}\right)^{4}
$$

We obtain analogously


Fig. 1

$$
\operatorname{Im} K_{11}=\frac{1}{2 R} \beta h(\alpha) \operatorname{Im}(i \bar{\theta})
$$

so that

$$
K_{11}=\frac{1}{2 R} \beta h(\alpha) i \theta
$$

Substituting the estimate found into (4.2) and (4.4), we obtain

$$
\begin{gather*}
h_{11}=-h_{12}=\frac{\beta h(x) i \theta}{2 R \sqrt{1-\alpha^{2}}} x_{1}(r)  \tag{4.5}\\
h_{21}=h_{22}=\frac{\beta h(x) i \theta}{2 R \sqrt{1-\alpha^{2}}} x_{2}(r)
\end{gather*}
$$

Let us apply successive approximations to (4.3). Let us take the static solution (3.3) as the first approximation

$$
\omega_{1}(r)=A x_{1}(r), \omega_{2}(r)=i A x_{2}(r)
$$

By using the estimate (4.5) we obtain the first approximation solution of the system (4.3) as

$$
\omega_{1}(r)=A_{*} x_{1}(r), \omega_{2}(r)=i A_{*} x_{2}(r) \quad\left(A_{*}=1+a \gamma h(\alpha) i \theta\right)
$$

In a first approximation the solution of (2.7) has the form

$$
\varphi_{1}(r)=2 A_{*} \cos \left(a \ln \frac{R-r}{R+r}\right), \quad \varphi_{2}(r)=2 A_{*} \sin \left(a \ln \frac{R-r}{R+r}\right)
$$

5. We find the reaction of the half-space (in the static case $\theta=0$ ) by the methods of integrating multivalued functions

$$
\begin{aligned}
P= & 2 \pi \int_{0}^{R} \sigma_{z}(r, 0) r d r=2 \pi \mu_{*} \int_{-R}^{R} \varphi_{1}(t) d t= \\
& 4\left(\lambda_{*}+\mu_{*}\right)[1+a \gamma h(\alpha) i \theta] \ln \left(\frac{\lambda_{*}+3 \mu_{*}}{\lambda_{*}+\mu_{*}}\right) b_{0} R
\end{aligned}
$$

Let us investigate the behavior of the stresses at the edge of the stamp. Let us note that because of the properties of $\varphi_{1}(t)$ and $\varphi_{2}(t)$ the relationships (2.2) can be represented as

$$
\begin{aligned}
& \frac{1}{2 \mu_{*}} \sigma_{z}=\frac{\varphi_{1}(r)}{\sqrt{R^{2}-r^{2}}}-\int_{r}^{R} \frac{t\left[\varphi_{1}(t)-\varphi_{1}(r)\right]}{\left(t^{2}-r^{2}\right)^{3} 2} d t \\
& \frac{1}{2 \mu_{*}} \tau_{r z}=\frac{\varphi_{2}(r)}{\sqrt{R^{2}-r^{2}}}-\int_{r}^{R} \frac{r \varphi_{\mathrm{z}}(t)-t \varphi_{2}(r)}{\left(t^{2}-r^{2}\right)^{2 / 2}} d t
\end{aligned}
$$

We set $t=R$ th $1 / 2 \xi, r=R$ th $1 / 2 x$, so that

$$
\begin{aligned}
& \frac{1}{2 \mu_{*}} \sigma_{z}=2 A \operatorname{ch} \frac{x}{2}[\cos (a x)+\varphi(x)], \quad \varphi(x)=\int_{x}^{\infty} \frac{\psi_{1}(\xi, x)}{\psi_{2}(\xi, x)} d \xi \\
& \psi_{1}=\operatorname{th} \frac{\xi}{2} \sin \left(a \frac{\xi-x}{2}\right) \sin \left(a \frac{\xi+x}{2}\right)\left(\operatorname{c} \frac{x}{2}\right)^{1 / 2} \\
& \psi_{2}=\left(\operatorname{th} \frac{x}{2}+\operatorname{th} \frac{\xi}{2}\right)^{3 / 2}\left(\operatorname{sh} \frac{\xi-x}{2}\right)^{3 / 2}\left(\operatorname{ch} \frac{\xi}{2}\right)^{1 / 2}
\end{aligned}
$$

The estimates

$$
\begin{aligned}
& \left|\frac{\psi_{1}}{\psi_{2}}\right|<\frac{|a|}{2 \sqrt{2}}\left(\operatorname{th} \frac{x}{2}\right)^{-3 / 2}\left(\operatorname{sh} \frac{\xi-x}{2}\right)^{-1 / 2} \\
& |\varphi(x)|<\frac{|a|}{\sqrt{2}}\left(\operatorname{th} \frac{x}{2}\right)^{-3 / 2} \int_{0}^{\infty}(\operatorname{sh} u)^{-1 / 2} d u<\frac{2 \ln 3}{\pi}\left(\operatorname{th} \frac{x}{2}\right)^{-3 / 2}
\end{aligned}
$$

are valid, hence $\varphi(x)$ is a continuous function and $|\varphi(x)|<1$ starting with some $x$. Therefore, the equation $\cos (a x)+\varphi(x)=0$ has an infinite number of zeros and the stress $\sigma_{z}$ oscillates at the edge of the stamp. The oscillation of $\tau_{r z}$ is proved analogously. The same phenomenon evidently holds also in dynamics, at least for low vibration frequencies.

It should be noted that the method developed above is applicable for arbitrary $\Lambda$ and $M$. However, the structure of $h(\alpha)$ is considerably more complex in the general case. In the particular case of an elastic medium $\alpha$ and $\theta$ take on only real positive values.
In conclusion, the author is grateful to L. A. Galin for attention to the research.

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ON THE PROBLEM OF THE RELATIONSHIP BET WEEN
THE SCHWARZSCHILD AND TOLMAN METRICS

PMM Vol. 37, N84, 1973, pp. 739-745<br>K.P.STANIUKOVICH and O.Sh.SHARSHEKEEV<br>(Moscow, Frunze)<br>(Received September 5, 1972)

The problem of the relationship between the Schwarzschild and Tolman metrics has occupied the attention of many workers. Although the solutions given in $[1-3]$ satisfy the equations of the general relativity theory (OTO) (*), they contradict the correspondence principle. This means that for $G \rightarrow 0$, the interval is not transformed into the interval of the special relativity theory (CTO) (*), while for $c \rightarrow \infty$, the solutions do not become Newtonian. This is apparently caused by the unfortunate choice of the coordinates in the Tolman frame of reference. Papers [4,5] illustrate particular cases of a correct passage from one metric to the other.

In the present paper a general method of obtaining solutions is proposed in which the passage from one frame of reference to the other satisfies the correspondence principle.
The intervals in the co-moving frame of reference and in the central frame of reference are, respectively.

$$
\begin{align*}
-d s^{2} & =-c^{2} d \tau^{2}+e^{\omega} d R^{2}+r^{2} d \Omega^{2}  \tag{1}\\
-d s^{2} & =-e^{2} c^{2} d t^{2}+e^{\lambda} d r^{2}+r^{2} d \Omega^{2}  \tag{2}\\
\left(d \Omega^{2}\right. & \left.=d \theta^{2}+\sin ^{2} \theta d \varphi^{2}\right)
\end{align*}
$$

Since $r=r(c \tau, R)$ and $c t=c t(c \tau, R)$, we have

$$
\begin{aligned}
& d r=r^{\bullet} c d \tau+r^{\prime} d R, c d t=c t^{*} c d \tau+c t^{\prime} d R \\
& \left(r^{\prime}=\partial r / c \partial \tau, r^{\prime}=\partial r / \partial R, c t^{\prime}=c \partial t / c \partial \tau, c t^{\prime}=c \partial t / \partial R\right)
\end{aligned}
$$

Substituting these differentials into (2), equating the coefficients accompanying $c^{2} d \mathrm{t}^{2}$ and $d R^{2}$ and remembering that the coefficient of $2 c d \tau d R$ is zero, we obtain

$$
\begin{equation*}
e^{\nu} c^{2} \dot{t}^{2}-r^{2} e^{\lambda}=1, \quad e^{\lambda} r^{\prime 2}-c^{2} t^{\prime 2} e^{v}=e^{\omega}, \quad e^{\lambda} r^{\circ} r^{\prime}-c \dot{t}^{\circ} c t^{\prime} e^{\nu}=0 \tag{3}
\end{equation*}
$$

from which, eliminating $e^{\lambda}$ and $e^{\nu}$, we have

$$
\begin{align*}
& e^{\lambda}=e^{\omega} /\left(r^{\prime 2}-r^{\cdot 2} e^{\omega}\right), e^{\nu}=r^{\prime 2} /\left\lfloor c^{2} t^{-2}\left(r^{\prime 2}-r^{-2} e^{\omega}\right)\right\rfloor  \tag{4}\\
& \left(e^{\omega} c t^{\prime} r^{\cdot}-c t^{*} r^{\prime}\right)\left(c t^{*} r^{\prime}-c t^{\prime} r^{\circ}\right)=0
\end{align*}
$$

[^0]
[^0]:    *) Editors note. The abbreviations (OTO) and (CTO) are used in the relevant Soviet literature and stand for "general relativity theory" and "special relativity theory", respectively.

